

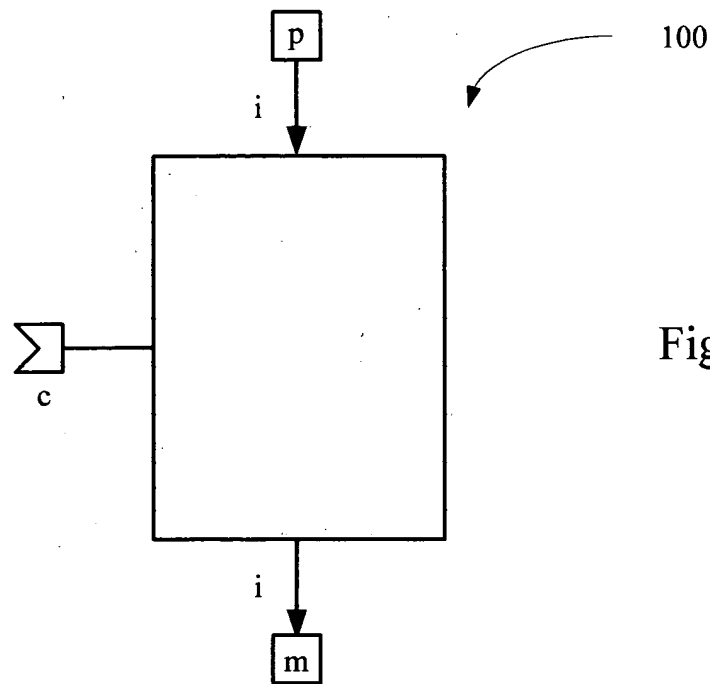


Figure 1A

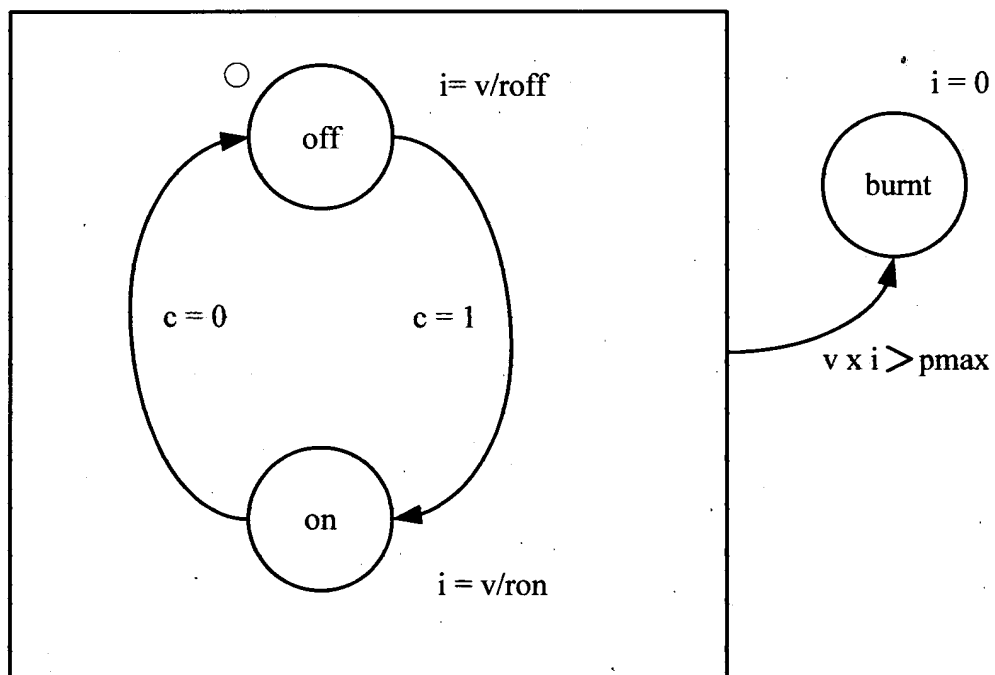


Figure 1B

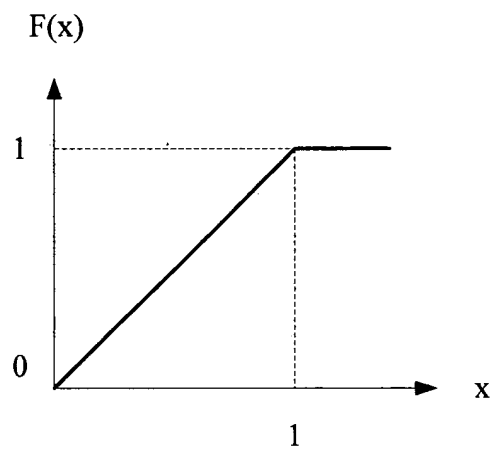


Figure 2A

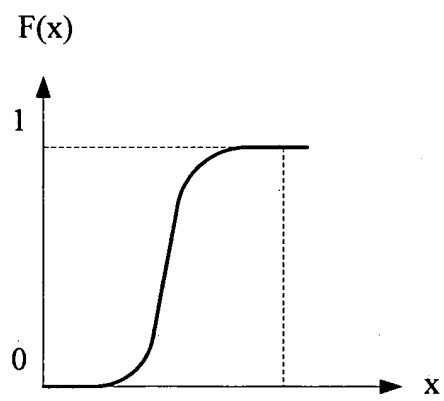


Figure 2B

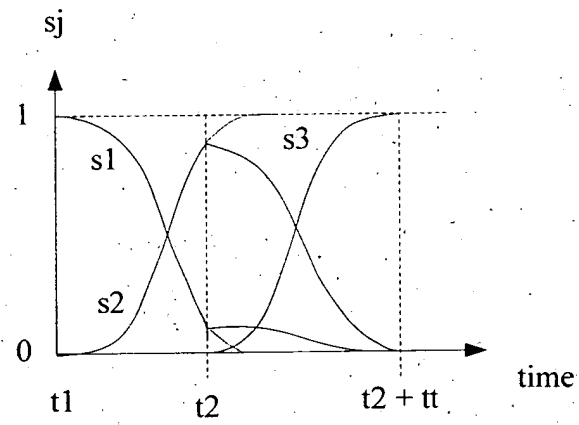


Figure 3A

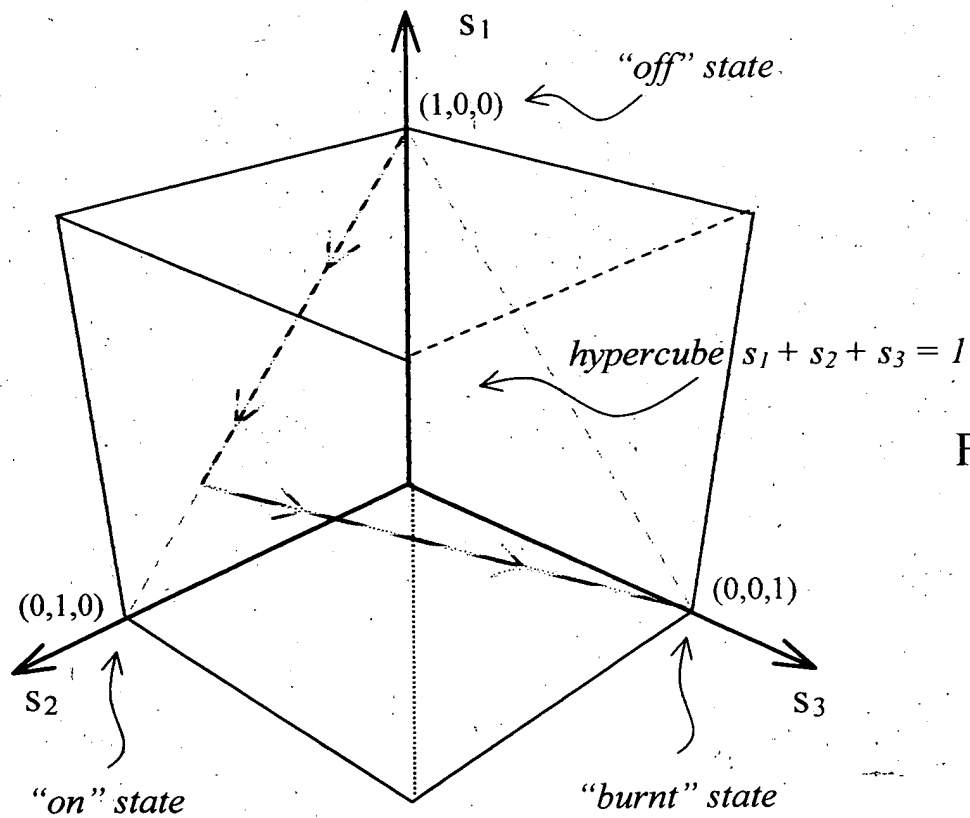
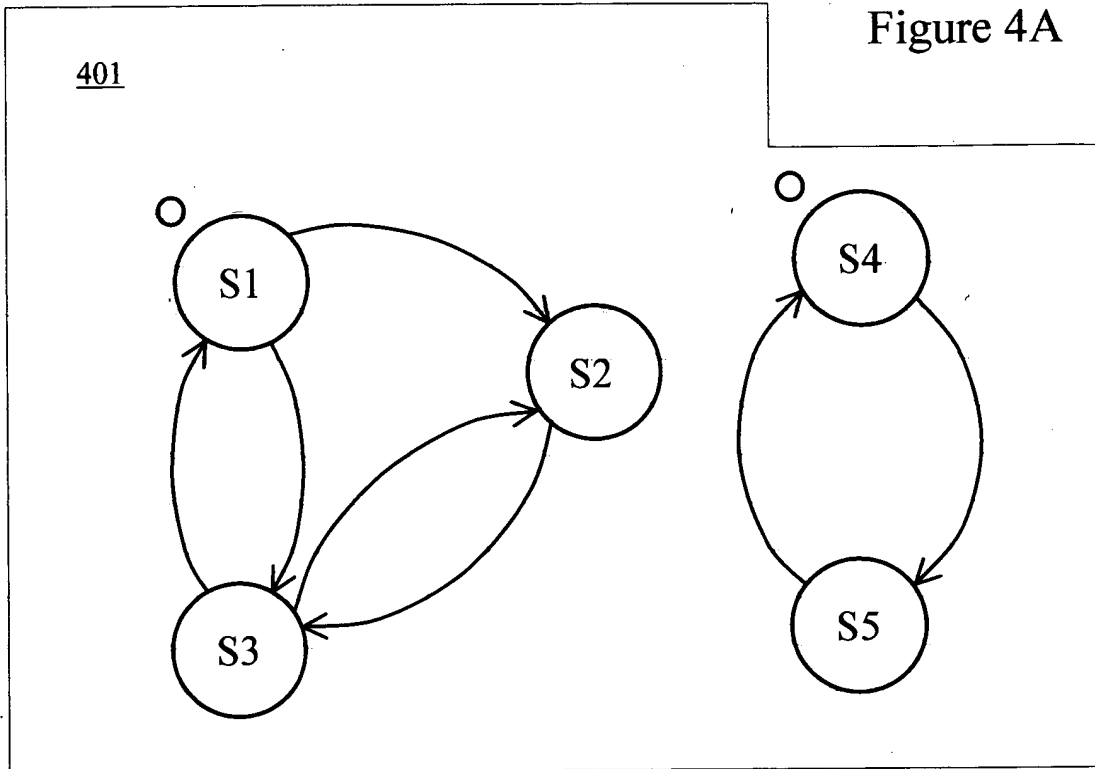


Figure 3B

Figure 4A



402

variable \ state	x_1	x_2	x_3	x_4
S1				
S2				
S3				
S4				
S5				

Figure 4B

variable combination	x_1	x_2	x_3	x_4
1	S1	S1	S4	S4
2	S1	S3	S4	S4
3	S2	S1	S4	S4
4	S2	S3	S4	S4
5	S1	S1	S5	S5
6	S1	S3	S5	S5
7	S2	S1	S5	S5
8	S2	S3	S5	S5

403

Figure 4C

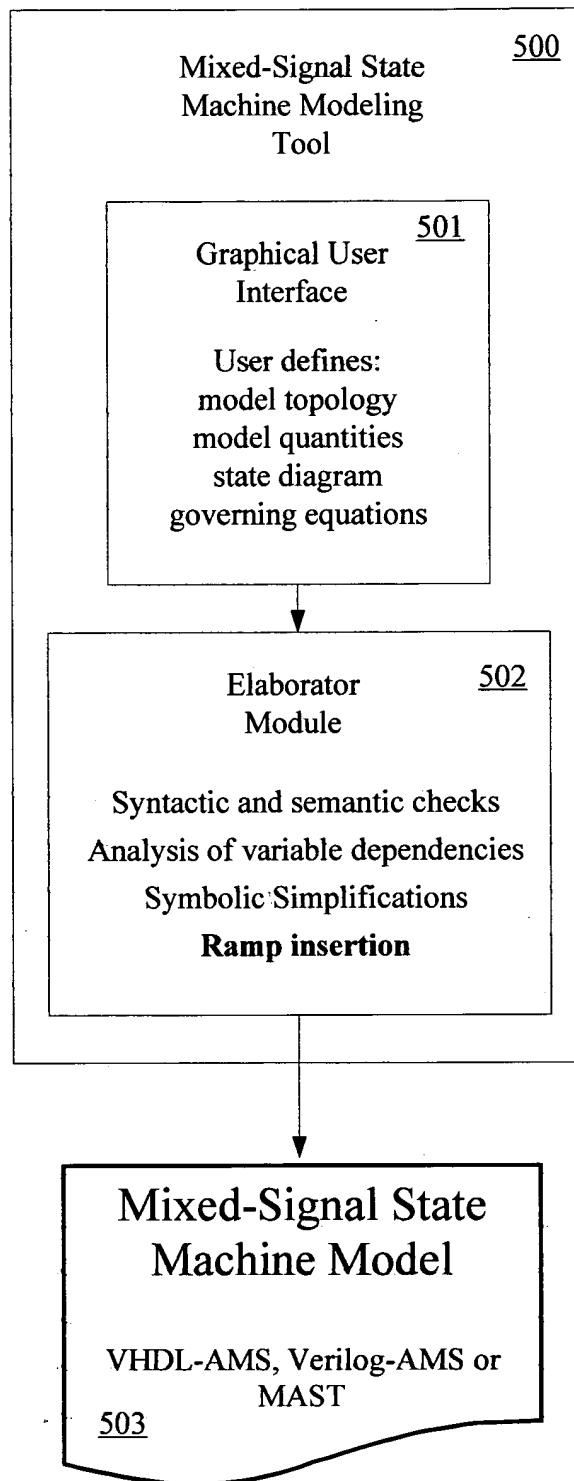


Figure 5

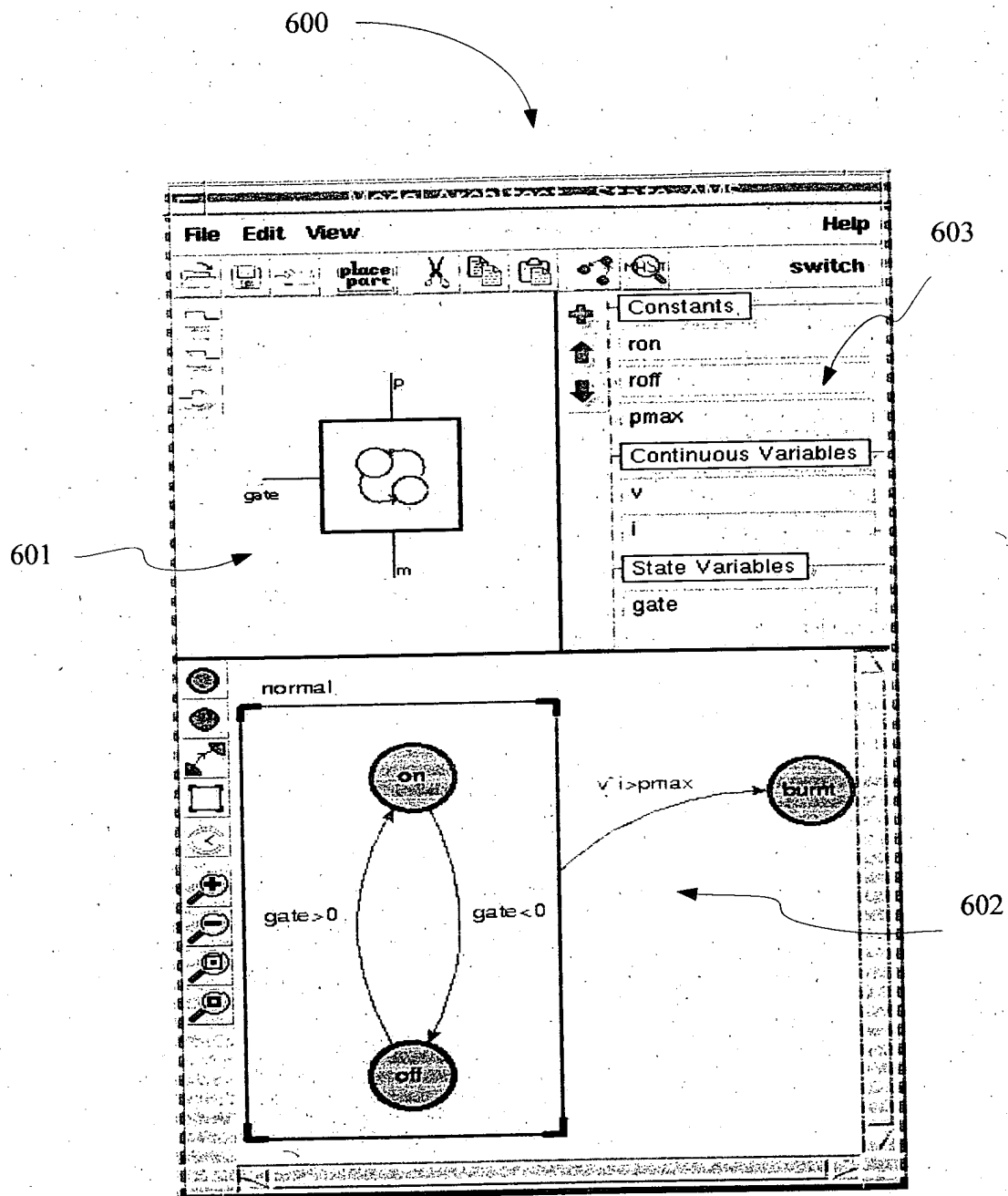


Figure 6A

610

Name: on

Comment:

Constraint Definition

Variable	Equation
i	v/ron

Initial Action

Entry Action

Exit Action

OK **Cancel**

Figure 6B

620

Condition:

Comment:

Priority level: 

Transition Action

Continuity

Transition time (s):

Transition profile: 

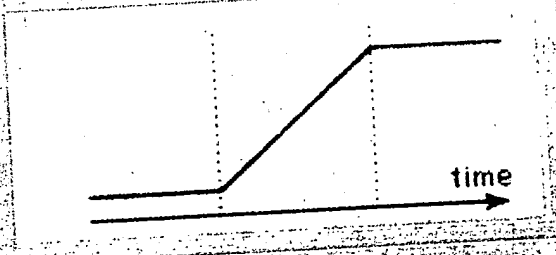


Figure 6C